

USING XML FOR SIMULATION MODELING

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ABSTRACT

XML represents a new way of organizing information and knowledge of the World Wide Web, using markup languages. Whereas HTML is used for presentation-specific content, XML builds upon its SGML lineage to separate content from presentation, and provide a semantic labeling for elements that comprise a document. With XML, the concept of “document” is broadened to include an encapsulation of information and knowledge, and not only a flat medium. This suggests that XML can be used for model specification and computer simulation. With this in mind, we have used XML to create two modeling specification languages: MXL and DXL. We begin by overviewing XML, discussing MXL and DXL, and then showing an example of how the languages are employed in the modeling process, and can be used with a variety of presentations.

1 INTRODUCTION

Our present work in XML started with earlier projects for supplying users with code libraries for simulation. Around 1990, we created SimPack (Fishwick 1992), which was originally a set of C source, libraries, and executables. The most significant part of SimPack was its support for discrete event simulation, with substantial segments of code for future event list handling and queuing. This latter part was recoded and re-engineered as OOSIM using C++ and object-oriented design principles. The Object-Oriented Physical Multimodeling (Fishwick 1995) (OOPM) toolkit was built using OOSIM to provide the user with a Tcl/Tk graphical front end for multimodeling. We created support for simulating several key types of models including Finite State Machines (FSM), Functional Block Models (FBM), Petri nets, and differential equations.

While this work was substantial and novel for its time, we found ourselves swept along with the World Wide Web phenomenon in an effort to broaden the simulation and modeling experience in a browser environment. This re-

sulted in the area of web-based simulation (Fishwick 1996, Page et al. 2000), which had good coverage at conferences and in special journal issues. The Web promised a different way of encoding model components, finding information, and a way of doing simulation using client-server mechanisms. For example, it was now possible to run a queuing simulation inside of a web browser. CGI scripts are one method allowing for server side execution, and Java applets and programs enable client side execution.

Most of the work in web-based simulation was just that—a focus on *simulation*, narrowly defined as the execution of models, rather than on the specification or presentation of them. To the extent that simulation also embodies the modeling process and the structure and form of models, we have embarked upon a research agenda predicated on specifying and presenting models. The natural intersection of the web and modeling can be found in the XML standard. Learning XML is significantly different than learning HTML, which is fairly small and easy to grasp. The elements of XML are straightforward; however, there are a very large number of associated XML technologies (Consortium 2002), each of which is in a different state of recommendation. While XML simplifies on the SGML standard, there remains a steep learning curve for mastering the important XML technologies and software.

2 MULTIMODELING & RELATED WORK

The focus of the *rube* Project defined further in Sec. 5, is on two characteristics of models: (1) multimodeling and (2) customization, with the second characteristic being one aspect of the first. To have “multiple” models can mean one of several things:

- *Multiplicity*: The modeling scheme supports more than one model instance;
- *Heterogeneity*: The modeling scheme supports more than one model type;

- *Hierarchy*: The modeling scheme supports a hierarchy of model instances;
- *Customization*: The modeling scheme supports alternate presentations for the same model type.

Multimodeling can be viewed using different dimensions (Fishwick 1991, Fishwick 1995). The most basic requirement is that to have a multimodel means that you have more than one model (multiplicity). If one has more than one model, the simplest way of connecting, or coupling, them together is through construction of an intra-component interface. An example is that one data flow model connects, via an interface, to an adjacent one. Heterogeneity creates yet another dimension by suggesting that categorically different types can be connected together, for example a data flow model connects to an FSM. These interfaces must be well-defined with matching data types, otherwise, it will not be possible to successfully simulate the multimodel. Zeigler (Zeigler, Praehofer, and Kim 2000) et al. use the term *closure under coupling* to ensure a workable model that is capable of being simulated under such conditions.

The ability to encapsulate one model inside of another is an issue of hierarchy, and this is yet another dimension to multimodeling. For example, one can take a circuit model, and in one of the components, declare a complete circuit, which in turn may have subdivisions into still further modeling levels. The last assumption of customization suggests that a modeling scheme supports different views and sensory interfaces for the same model specification.

Our goals are to support all four multimodeling assumptions. The use of XML is still fairly new in modeling and simulation, but we envision an increased awareness and use of it as a fundamental tool for both model specification and execution. Our emphasis on customization is central to *rube*. Other researchers are tackling similar problems on the other aspects of multimodeling. Both Modelica (Tiller 2001) and DEVS (Zeigler, Praehofer, and Kim 2000) have similar goals regarding the notion of the first three listed assumptions, with some notable exceptions. For example, Modelica's emphasis seems targeted at electro-mechanical systems, even though its large scope permits it to have effects outside of this domain. DEVS is largely a low-level formal specification language. To date, neither of these languages have an XML presence, but this may change in the future.

3 XML

XML, eXtensible Markup Language, emerged in the mid 90s as a new language for the Web. To see why it emerged, we need to begin with a look at the ubiquitous HTML (HyperText Markup Language). HTML is a tag-based ASCII language for defining content on the web. In HTML, one can define both text and graphics-based markup in the form of

web *pages*. The typical browser, such as Internet Explorer or Netscape, has an option "view source," which allows the user a way to see the underlying HTML that comprises web pages. A sample piece of HTML looks like:

```
<H1>History of Light Bulbs</H1>
<H2>by
<A href='`http://www.lightbulb.com``'>
Edison</A></H2>
<P>
Our story begins ...
```

<H1> and </H1> are opening and closing tags, respectively, so that anything placed in between these tags is considered to represent an "H1". H1 is a header with a size index of 1 to reflect that it is a primary header, unlike H2, which is secondary. While theoretically, H1 and H2 could mean anything, they are given precise meanings in HTML, and furthermore, they are given precise presentations. That is, when you specify H1, you expect to obtain relatively large, bold-face, header text. Continuing with our example, <P> denotes a paragraph, and the (<A>,) pair specify a hyperlink to a web page. When a web designer codes these HTML primitives, they know exactly what to expect from a human-computer interaction perspective.

The problems with HTML are numerous, but one of the chief complaints is that it is inflexible with regard to the multiplicity of display devices that are on the market. A technique called Cascading Style Sheets (CSS) provides some relief by allowing one to have alternate display styles for hand held PDAs and desktops, but we'd like more flexibility in separating *content* from *presentation*. We would like to be able to use TITLE or AUTHOR instead of H1 and H2, for example, without explicitly defining how these will appear to the user. We want to define a *semantic web* (Berners-Lee, Hendler, and Lassila 2001).

XML allows us to create tags such as <TITLE>, and is based on SGML (Standard Generalized Markup Language), which preceded it. Goldfarb (Goldfarb 1990) describes a language that originated prior to the web, and whose goals were generalized markup to satisfy a large number of type-setting requirements and devices. A language was needed to build upon the flexibility of SGML, without the presentational limitations of HTML and complexity of SGML, and this language evolved into XML. At first, one might question the purpose of XML, since it really is nothing more than tree-structured text. XML supports reading by both humans as well as computers, since its syntax is simple. Furthermore, XML suggests that application-specific areas of the web are not about documentation, per se, but about encoding information and knowledge. For example, CML (CML 2002) encodes the atomic structure of molecules. How they molecules appear to the user may depend on a wide variety of factors, but by standardizing on CML, users can take

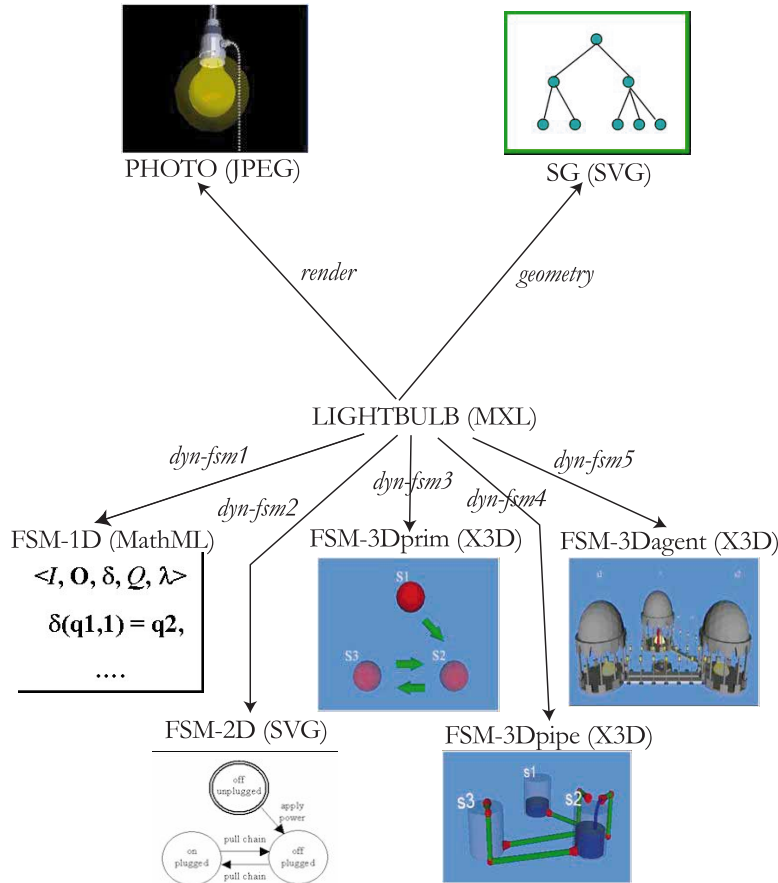


Figure 1: Semantic Network of Lightbulb System Models

advantage of tools that import and export CML as a fundamental data type. Likewise, MathML (MathML 2001) defines the content of mathematical expressions independent of presentation. Both SGML and XML bear striking resemblance to many other markup languages, such as \LaTeX with the primary difference being that the former are meant for generalized markup of information, and so create the possibility of communicating and dispersing and managing general semantic content throughout the web.

4 MODEL CUSTOMIZATION

I will overview the architecture of the *rube* Project, but first, let's discuss the nature of modeling so that we can gain a foothold in our search for new modeling techniques. Modeling is the act of choosing materials in such a way as to capture some aspect of a target scene or object. For simulation, this *aspect* is one of dynamics. We seek to capture concepts of state, event, and time in the model that we craft. Let's suppose that the object of interest is a lightbulb, and that we wish to capture a simple behavior dictated by state transitions: OFF-UNPLUGGED, OFF,

and ON. OFF-UNPLUGGED is the state where there is no applied power, whereas OFF is the state once the power is applied, and yet the switch activated by a pull-cord remains in the off-position. ON is the state when the switch is turned on. Consider Figure 1, which defines a semantic network expressing several model types. This figure is a graphical realization of an equivalent RDF (Framework 2002), which specifies an XML framework for specifying ontologies.

A computer graphic 2D rendering, or photograph, yields the model in the upper left of Fig. 1. Labeled, PHOTO, this is a kind of model of the lightbulb system, since it presents some visual aspects of the system. Likewise, the more geometrically-oriented SG in the upper-right of Fig. 1, is short for Scene Graph, and shows a scene graph specifying the lightbulb's geometric structure. The acronym to the left of the parentheses in Fig. 1 specifies the name of a model, and the one inside the parentheses, defines the file type (JPEG for the PHOTO, and SVG for SG).

The models below LIGHTBULB are all ones associated with the dynamics of the lightbulb. These dynamics are captured as a 3 state FSM whose states are those previously mentioned. The model may be presented as 1D, 2D, or

3D objects, and moreover, the presentations may be customizable so that one may both encode and view the FSM as flowing water between tanks (FSM-3Dpipe) or an avatar moving between gazebos (FSM-3Dagent). An important aspect of Fig. 1 is that all of these models can be viewed as styles generated from the core MXL file, to be discussed in Sec. 5.3. This results in a unique philosophical view of model specification and presentation: namely, that the core specification in MXL is largely independent of how the models are presented. This view, or perspective, promotes personalization and customization of the modeling interface, allowing for both native and artificial cultural adaptations to the way in which models are experienced.

5 RUBE PROJECT

5.1 Architecture

rube is a project that has engaged us for the past two years, as a follow on to our work in multimodeling and web-based modeling and simulation. The purpose of *rube* is to facilitate dynamic multimodel construction and reuse within a 3D, immersive environment. Within the context of Modeling and Simulation (M&S), this project reflects a “next generation” philosophy about modeling (Fishwick 2002). The project is vast in scope, but focused on this purpose. We began work in *rube* using the Virtual Reality Modeling Language (VRML) as our primary vehicle for specification of both geometry and dynamics. VRML is the current ISO standard for 3D graphics on the web. This was done by using the “Prototype” extensibility mechanism of VRML. In the past year, however, we have progressed toward XML as a way to declare model and presentation semantics. Figure 2 displays the structure of *rube*. We begin with two files: scene and model. The scene file contains visual objects and components that are presentations of corresponding formal dynamic model equivalents in the model file. Thus, the model file captures the topology of the dynamic model, whereas the scene file captures what the components and connections “look like.” This can be taken further by considering senses other than vision, but since vision is our primary apparatus for interacting with the world, we built *rube* with the idea of viewing models in 1D, 2D, or 3D. By “1D,” I am referring to a textual, or typographical, presentation.

5.2 X3D

We have been using two scene languages, one of which is denoted in Fig. 2: X3D. X3D, or eXtensible 3D, is the follow-on standard to VRML. The 2D scene language, other than X3D, is SVG (Scalable Vector Graphics). Both SVG and X3D support internal scripting in Javascript and Java so that the scenes can be made dynamic with mov-

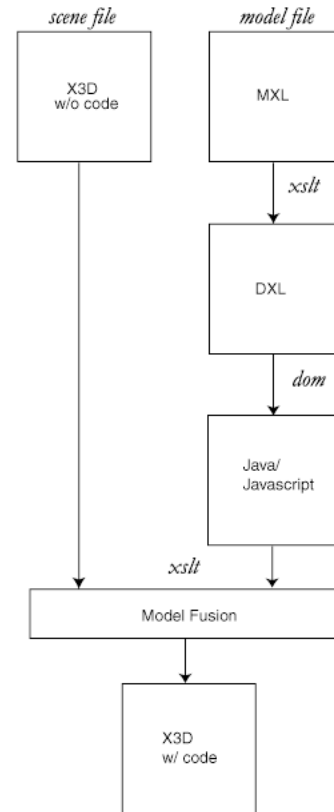


Figure 2: *rube* Architecture

ing objects over time. X3D contains primitives such as cone, cylinder, and sphere, as well as more flexible geometric structures such as NURBS (Non-Uniform Rational B-Splines), and polygonal meshes. SVG contains similar 2D geometries. Presentation in 1D involves languages such as HTML, XHTML (an XML version of HTML), and MathML. The following is an excerpt from an X3D file:

```

<X3D>
<Scene>
  <NavigationInfo type=' "EXAMINE"
    "ANY" ' />
  <Transform DEF="S1"
    translation="2.9E-8 5.0 -6.0">
    <children>
      <Shape >
        <appearance>
          <Appearance >
            <material>
              <Material
                diffuseColor="1.0
                  0.0 0.0"/>
            </material>
          </Appearance>
        </appearance>
      </Shape >
    </children>
  </Transform>
</Scene>
  
```

```

    </appearance>
  </geometry>
  <Sphere />
</geometry>
</Shape>
</children>
</Transform>

```

The file, like all XML files, is ASCII and describes a scene graph (Foley, van Dam, Feiner, and Hughes 1999). A scene graph is a tree of transform nodes ending in leaf nodes, which define the individual pieces of geometry needed to create the whole after working recursively upward through the hierarchy. This graph defines the visualization of one red sphere of FSM-3Dprim from Fig. 1.

5.3 MXL

Given a desired appearance in Sec. 5.2, we can define the formal structure using MXL (Multimodeling eXchange Language) of the lightbulb 3 state FSM. The following is an excerpt from the complete MXL file:

```

<MXL>
<model id="FSM2S2T" type="FSM">
  <topology type="GRAPH">
    <node id="S1" type="STATE"
      start="TRUE">
      <script id="S1.js"
        func="S1_func"/>
    </node>
    <node id="S2" type="STATE">
      <script id="S2.js"
        func="S2_func"/>
    </node>
    <node id="S3" type="STATE">
      <script id="S3.js"
        func="S3_func"/>
    </node>
    <edge id="T12" type="TRANSITION"
      begin="S1" end="S2"
      data_type="INTEGER">
      <script id="T12.js"
        func="T12_func"/>
    </edge>
    <edge id="T23" type="TRANSITION"
      begin="S2" end="S3"
      data_type="INTEGER">
      <script id="T23.js"
        func="T23_func"/>
    </edge>
    <edge id="T32" type="TRANSITION"
      begin="S3" end="S2"
      data_type="INTEGER">

```

```

      <script id="T32.js"
        func="T32_func"/>
    </edge>
  </topology>

```

All semantics for the FSM are encoded in Javascript (.js suffix) files. The MXL file is translated into DXL (next section) using XSLT (XML Style Sheet Transformation). XSLT provides a sophisticated pattern language for transforming one XML document into another document, often in either XML or XHTML. The translation is most generally accomplished using a network or pipe containing a series of transformations, capable of efficiently and easily modifying documents.

5.4 DXL

After specifying the scene and model files in Fig. 2, then *rube* begins its processing. The first step is to generate a DXL (Dynamics eXchange Language) file. While the structure of MXL contains model-specific element and attribute names, DXL serves as an assembly layer, with a small number of components. The DXL file contains blocks, each having input and output ports and optional local variables. Blocks are tied together using connectors. An excerpt from the DXL file generated from the MXL file in Sec. 5.3 follows:

```

<DXL>
<block id="IN">
  <port id="IN.OP1" type="OUTPUT"
    target="S1.IP1"
    data_type="INTEGER"></port>
  <definition id="IN.js"
    func="IN_func">
  </definition>
</block>
<block id="S1">
  <port id="S1.IP1" type="INPUT"
    source="IN.OP1"
    data_type="INTEGER"></port>
  <port id="S1.OP1" type="OUTPUT"
    target="T12.IP1"
    data_type="INTEGER"></port>
  <port id="S1.OP2" type="OUTPUT"
    target="OUT.IP1"
    data_type="INTEGER"></port>
  <definition id="S1.js"
    func="S1_func">
  </definition>
</block>

```

DXL translates directly into Java or Javascript using DOM (Domain Object Model). DOM is the way in which programs can externally access the internal XML tree from outside.

DOM allows code to traverse the tree using pattern-matching based on the XPATH specification. The code is augmented by SimPackJ/S, which is a Java/Javascript version of SimPack.

5.5 Model Fusion

Given the original scene graph and the Java or Javascript created from DXL, we are in a position to merge these two to create a scene graph with embedded code. This is then placed into a browser and the user engages and navigates the scene using the interactivity afforded by the code. The last three snapshots in the bottom-right part of Fig. 1 illustrate 3D scenes containing interactive FSM models.

6 CONCLUSIONS

A preliminary observation is one concerning XML. Its definition and use are bound to have dramatic effects on modeling and simulation, with *rube* serving as one type of system which uses XML as a core language. Using XML in the core has advantages and disadvantages. The advantages that I've overviewed include the separation of content from presentation, and XML's prominence in the web community; it is here to stay around for a long time, or evolve into something even more powerful and flexible. The disadvantages of using XML are in sacrificing some speed gained through more proprietary interfaces, and in not knowing which XML document types will be around long enough to use. Like the field of computer science, in general, XML is a very fast moving target if one strays into various types, powerful as they may be. Document types progress in stages from notes to working drafts, candidate and proposed recommendations, and finally W3C recommendations. So, there is the uncertainty associated with the acceptance stage, but reaching the final stage is no guarantee of permanence.

Summarizing the paper, our team has constructed a basic XML-based modeling and simulation system that serves all four multimodeling assumptions presented in Sec. 2. The software is not yet complete since we still need to test the basic model types, and provide new ones such as Petri Nets and System Dynamics graphs. In the simulation classes at the University of Florida, we have conducted surveys to determine the relative effectiveness of allowing students the ability to choose their own presentations, not only for the system being modeled, but the model as well. Students have overwhelmingly voted highest for the ability to customize model structures, while noting the inherent inefficiencies in constructing 3D models. We see the majority of efficiency problems as being addressable by technology advancement as hardware gets cheaper and faster, and yet much remains in creating more accessible 3D modeling programs. 3D is still fraught with the usual problems of navigation and selection.

The robustness of the system will be tested this Fall 2002, with the first use of *rube* by students in the undergraduate and graduate simulation classes. As part of our work in the three-year old Digital Arts and Sciences curricula, we also plan to employ *rube* as a way to not only rephrase and represent dynamic model structures, but also static structures, such as simple mathematical formulae cast in MathML. The idea of customization and personalization of model structure naturally lends itself to the Arts, and so this activity helps to form a bridge between the Colleges of Fine Art and Engineering.

We need to continue our work at the architectural level or *rube*, to support XML as a fundamental data type, and to ensure that DXL is robust enough to serve as the foundation for future model types. We also need to make it possible for individual styles to be semi-automatically generated directly from MXL. To date, one must create both the *scene* and *model* files, without any help from *rube*. Next year, we hope to have a system in place, which in combination with XSLT, will permit styles to be more easily specified. Finally, we need to create more substantial, applied model structures with *rube*, since most of our present work is in making the system operational.

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