

NON-STATIONARY QUEUE SIMULATION ANALYSIS USING TIME SERIES

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ABSTRACT

In this work, we extend the use of time series models to the output analysis of non-stationary discrete event simulations. In particular, we investigate and experimentally evaluate the applicability of ARIMA(p, d, q) models as potential meta-models for simulating queueing systems under critical traffic conditions. We exploit stationarity-inducing transformations, in order to efficiently estimate performance measures of selected responses in the system under study.

1 INTRODUCTION

Analyzing the results produced by simulation models is certainly an area of utmost practical importance. On the other hand, the highly autocorrelated nature of simulation responses, namely in queueing systems, has challenged simulation analysts to propose ever more innovative approaches.

The use of classical time series models (Box, Jenkins, and Reinsel 1994) in the output analysis of stationary discrete event simulations was initially proposed by Fishman (1971). He suggested fitting an autoregressive model of order p , AR(p), to a simulation response, as an intermediate step for estimating reliable variability measures of the response (variance, confidence intervals). Later, Schriber and Andrews (1984) generalized that approach and used an automated procedure for fitting mixed autoregressive-moving average models, ARMA(p, q). In both cases, the authors reported poor performance results, namely, in the coverage rates of confidence intervals for simple queueing systems.

Contradicting the apparent incompatibility between queueing systems and time series models, Brandão and Porta Nova (1999) showed that most of those results could be related to either an insufficient simulation duration or an excessive initial bias. Keeping under control these two factors, very positive results were observed for an $M/M/3$ stationary queue under moderate and congested traffic situations.

This paper is organized as follows. In Section 2, we discuss the use of classical time series models to analyze the output of non-stationary discrete event simulations. In Section 3, we investigate the applicability of ARIMA models as potential meta-models for queueing system simulation under critical traffic conditions. Finally, in Section 4, we draw some conclusions and suggest further work in this area.

2 NON-STATIONARY SIMULATION

The output analysis of non-stationary discrete event simulations is conspicuously absent from the literature of stochastic simulation. The well-known asymptotic result, for simple queueing systems, that most response measures go to infinity when the utilization factor approaches one, seems to have convinced the simulation community that it was worthless to explore this topic. Uncontrolled evolution, explosive growth, are but two ways of characterizing a situation that has undoubted practical interest. During rush-hour periods, system breakdowns, etc., arrival rates do actually exceed processing rates. And much needed and useful information might be extracted from such non-stationary simulations, many "what if?" questions could be answered... What is the expected queue length at the end of a rush-hour period? What is the expected sojourn time for an entity arriving halfway through that period? It would be even more interesting if we could predict the evolution in time of these and other performance measures, without having to repeat time consuming simulations and subsequent output analysis. This is the main purpose of pursuing simulation meta-models: finding analytical models that are simpler but realistic representations of the computer programs implementing simulation models.

Since the output produced by stochastic simulation models is essentially composed of strongly autocorrelated time series, it seemed just natural to investigate the applicability of the classical time series models, ARIMA(p, d, q), as potential meta-models for non-stationary simulations. In

most scientific areas where the Box-Jenkins methodology is widely applied, data is scarcely available; that is the case, for instance, when econometric models are fit to a single realization of an economical time series. In contrast to that, we can choose any number of independent replications to analyze the output produced in discrete event simulation experiments. Thus, if we analyze the averaged responses across runs, instead of a single realization: (i) we reduce the time series variability; (ii) we are able to identify more clearly the *underlying* evolution of the response with respect to time; and (iii) we make the meta-model fitting process much easier. In addition, this is a valid fitting approach to autocorrelated data, contrarily to regression-based procedures. If the simulation responses are non-stationary in variance, it may be necessary to previously apply a variance-stabilizing transformation.

We illustrate our meta-modelling approach to non-stationary simulation with two case studies, two simple queues, with utilization factors greater than or equal to one, and we analyze the evolution of two responses: average queue length and average time spent in the system.

3 EXPERIMENTATION

In this section, we present and discuss the experimental evaluation of the applicability of $ARIMA(p, d, q)$ meta-models for the non-stationary simulation of two $M/M/s$ queueing systems—that is, with exponential inter-arrival and service times, and s identical parallel servers. We consider two distinct values for the utilization factor, $\rho = \lambda/(s\mu)$, where λ and μ represent the arrival and service rates, respectively: $\rho = 1$ (a critical traffic situation) and $\rho = 2$ (super-critical traffic).

We performed a Monte Carlo experiment consisting of 3000 independent replications of each simulation model with a *reference* duration of 60 time units for the following queueing systems:

- (i) An $M/M/1$ queue with super-critical traffic ($\rho = 2$); and
- (ii) An $M/M/2$ queue with critical traffic ($\rho = 1$).

The actual duration varied, because each run was only terminated when the last entity that had arrived before 60 time units left the system. The initial conditions for each model were an empty and idle system.

Queue lengths were collected at regular time intervals $\Delta_t = 0.5, 1.0$, with $t \in (0, 60]$; sojourn times were sorted according to the time interval in which the arrival had occurred. Then, for each time interval, the corresponding observations across 30 runs were averaged. Finally, the Box-Jenkins methodology was applied to the averaged time series of each response, through the identification, estimation and diagnostic checking of the $ARIMA(p, d, q)$ models.

Although we performed the experimentation for both interval widths, we only present the graphs corresponding to $\Delta_t = 0.5$, because the results are very similar.

3.1 A Super-Critical $M/M/1$ Queue

The super-critical traffic situation was created with an inter-arrival rate of $\lambda = 2$ and service rate of $\mu = 1$, producing the utilization factor $\rho = 2$.

Analyzing the average queue length for a typical set of 30 runs (see Figure 1, the hardly discernible dash-line), we can conclude that the process is non-stationary on the mean: there is a marked linear trend and the sample autocorrelation function (ACF) decreases very slowly to zero. In the figure, the sample partial autocorrelation function is also represented. The results produced by the fitted model are also represented (solid line) on the subgraph containing the original series (dash-line).

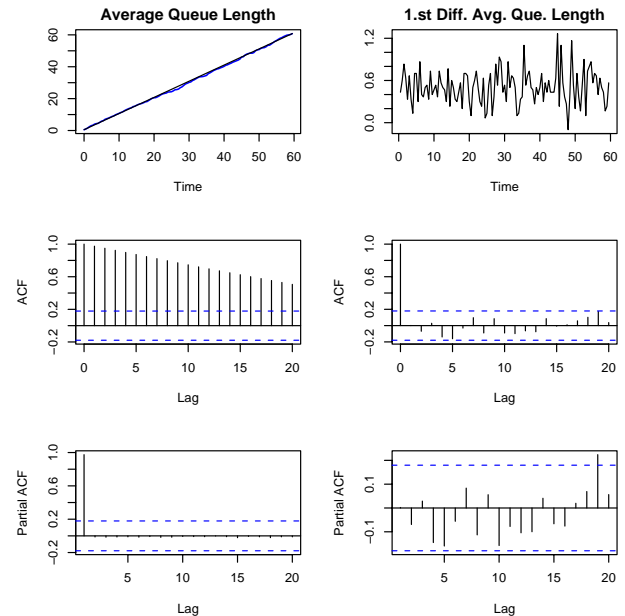


Figure 1: Average Queue Length ($M/M/1$, $\rho = 2$ and $\Delta_t = 0.5$)

Differentiating the series (see again Figure 1), we observed that it became stationary, without any statistically significant value on the ACF and PACF. This was also confirmed applying the Box-Ljung test. Thus, in this case, we can fit the $ARIMA(0, 1, 0)$ model to the average queue length. This is an example of the simplest possible $ARIMA$ model, where the first difference produces white noise. This process is called a random walk with drift, if it has a nonzero expected value, or simply a random walk, otherwise.

We repeated the analysis for the remaining 99 time series (each corresponding to an average of 30 runs) obtaining the results reproduced in Table 1. In more than 90% of

Table 1: Valid Fits for Average Queue Length ($M/M/1$ Queue, with $\rho = 2$)

ARIMA(0, 1, q) FITTED MODEL	TIME INTERVAL		ARIMA(p, 1, 0) FITTED MODEL	TIME INTERVAL	
	$\Delta_t = 0.5$	$\Delta_t = 1.0$		$\Delta_t = 0.5$	$\Delta_t = 1.0$
ARIMA(0, 1, 0)	91	93	ARIMA(0, 1, 0)	91	93
ARIMA(0, 1, 4)		1	ARIMA(1, 1, 0)		1
ARIMA(0, 1, 5)	1	3	ARIMA(2, 1, 0)	1	2
ARIMA(0, 1, 6)	1	2	ARIMA(3, 1, 0)		2
ARIMA(0, 1, 7)	3	1	ARIMA(4, 1, 0)	1	1
ARIMA(0, 1, 8)	2		ARIMA(5, 1, 0)	6	
ARIMA(0, 1, 9)	1		ARIMA(6, 1, 0)	1	1
ARIMA(0, 1, 10)	1				

the cases, the same ARIMA(0, 1, 0) model was consistently validated.

The 100 original series are represented in Figure 2, as well as the corresponding fitted series. Comparing the two subgraphs, we see that both series have basically the same behavior.

The mean values of the differentiated data (for all the 100 series) are, approximately, 0.5 (for the case $\Delta_t = 0.5$) and 1 (for the case $\Delta_t = 1.0$). This suggests that the average queue length is directly proportional to the elapsed time. This important conclusion is in agreement with a little-known asymptotic result obtained by Bailey (1964) for the $M/M/1$ queue: the mean of the queue length at instant t can be approximated by $(\lambda - \mu)t$ for $\lambda > \mu$, thus validating the approach and the results presented here. In the same Figure 2, we also represent Bailey’s result (the thick white line in the subgraph to the right).

A similar analysis was performed for the other response, the average sojourn time. In this case, differentiation did not produce white noise, except for a few data series. The original series, its first difference and the corresponding ACF and PACF are represented in Figure 3.

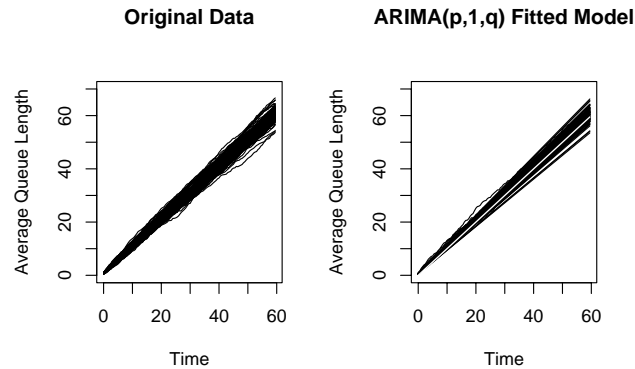


Figure 2: Original and Fitted Series: Average Queue Length ($M/M/1$ Queue, with $\rho = 2$ and $\Delta_t = 0.5$)

The number of different ARIMA($p, 1, q$) models that were actually fitted to the 100 series of average sojourn times are reported in Table 2. Although the order of the ARIMA($p, 1, q$) model required to cover about 90% of the original series increased substantially, we see that the fitted models keenly capture the global behavior of the data series—see Figure 4.

3.2 A Critical $M/M/2$ Queue

To create, now, a situation with a critical value for the utilization factor, $\rho = \lambda/(s\mu)$, we chose an arrival rate of $\lambda = 2$ and a service rate of $\mu = 1$, resulting in $\rho = 1$ for the utilization factor.

Analyzing, for this case, the average queue length series (dash-line in Figure 5), we can observe, as before, a clear

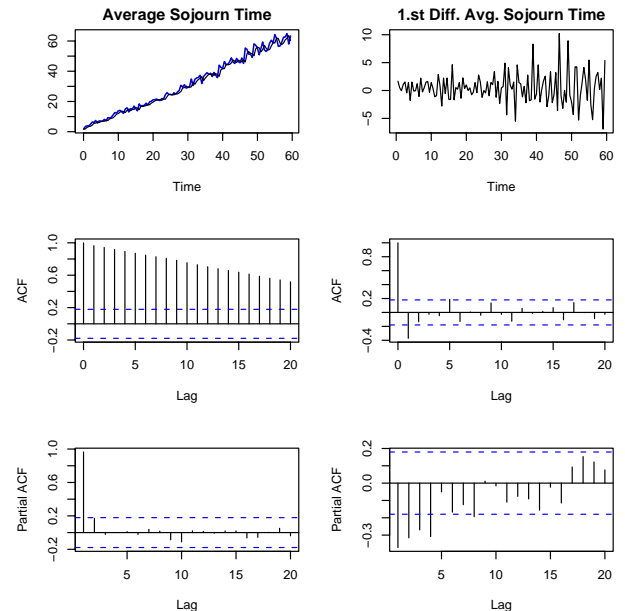


Figure 3: Average Sojourn Time ($M/M/1$ Queue, with $\rho = 2$ and $\Delta_t = 0.5$)

Table 2: Valid Fits for Average Sojourn Time ($M/M/1$ Queue, with $\rho = 2$)

ARIMA(0, 1, q) FITTED MODEL	TIME INTERVAL		ARIMA(p, 1, 0) FITTED MODEL	TIME INTERVAL	
	$\Delta_t = 0.5$	$\Delta_t = 1.0$		$\Delta_t = 0.5$	$\Delta_t = 1.0$
ARIMA(0, 1, 0)		14	ARIMA(0, 1, 0)		14
ARIMA(0, 1, 1)	27	11	ARIMA(1, 1, 0)	15	21
ARIMA(0, 1, 2)	18	25	ARIMA(2, 1, 0)	30	6
ARIMA(0, 1, 3)	16	23	ARIMA(3, 1, 0)	16	20
ARIMA(0, 1, 4)	16	21	ARIMA(4, 1, 0)	9	14
ARIMA(0, 1, 5)	12	5	ARIMA(5, 1, 0)	8	18
ARIMA(0, 1, 6)	8	1	ARIMA(6, 1, 0)	9	1
ARIMA(0, 1, 7)	2		ARIMA(7, 1, 0)	8	3
ARIMA(0, 1, 8)	1		ARIMA(8, 1, 0)	2	2
			ARIMA(9, 1, 0)	2	
			ARIMA(10, 1, 0)	1	1

linear trend on the data; again, the ACF decreases very slowly to zero indicating a non-stationarity on the mean. In solid line we represent the results produced by the fitted model. In spite of this promising start, this case ended up representing the greatest challenge to our analysis. Repeating the application of the Box-Jenkins methodology to the 100 average queue length responses, it was again possible to fit a large number of ARIMA(0, 1, 0) models. This seemed to suggest that simple differentiation would produce white noise. However, the predicted linear evolution failed to detect a marked nonlinear start of the actual responses.

Since the Box-Cox transformations frequently reduce nonlinearity, as well as heteroscedasticity, we applied them to the 100 averaged data series, obtaining the results reproduced in Table 3. Again, we can conclude that the ARIMA(0, 1, 0) is a good model for the transformed average queue length. In Figure 6 we represent the original series and the corresponding fitted series. We can see that,

except for a few extremal cases, the global behavior of the original series is now mostly captured. However, we may have to further explore new stabilizing transformations.

The results obtained for the average sojourn time in the $M/M/2$ queue, with $\rho = 1$, were very similar to those of the $M/M/1$ queue (see Figure 7).

We then tried to fit the same type of ARIMA(p, 1, q) models to the 100 series, obtaining the results presented in Table 4.

Again, differentiation did not produce a significant number of cases of white noise. In this case, the fitted ARIMA(p, 1, q) models had higher orders and they aptly

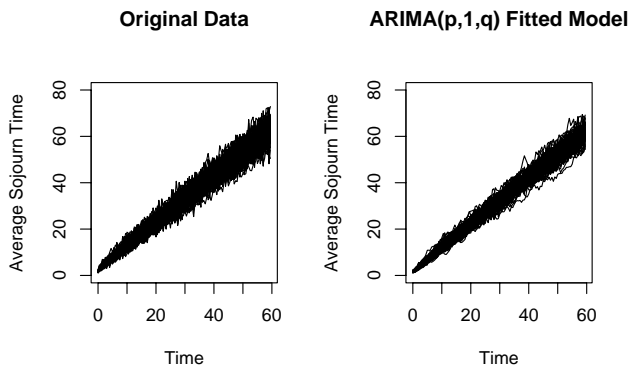


Figure 4: Original and Fitted Series: Average Sojourn Time ($M/M/1$ Queue, with $\rho = 2$ and $\Delta_t = 0.5$)

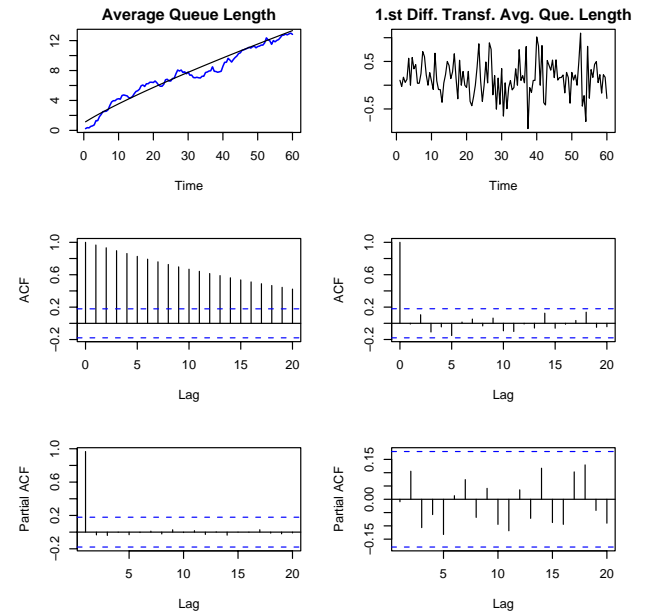


Figure 5: Average Queue Length ($M/M/2$ Queue, with $\rho = 1$ and $\Delta_t = 0.5$)

Table 3: Valid Fits for Average Queue Length ($M/M/2$ Queue, with $\rho = 1$)

ARIMA(0, 1, q) FITTED MODEL	TIME INTERVAL		ARIMA(p, 1, 0) FITTED MODEL	TIME INTERVAL	
	$\Delta_t = 0.5$	$\Delta_t = 1.0$		$\Delta_t = 0.5$	$\Delta_t = 1.0$
ARIMA(0, 1, 0)	91	89	ARIMA(0, 1, 0)	91	89
ARIMA(0, 1, 1)	3	1	ARIMA(1, 1, 0)	3	1
ARIMA(0, 1, 2)	3	4	ARIMA(2, 1, 0)	1	3
ARIMA(0, 1, 3)	2	5	ARIMA(3, 1, 0)	2	6
ARIMA(0, 1, 5)	1		ARIMA(4, 1, 0)	2	1
ARIMA(0, 1, 6)		1	ARIMA(5, 1, 0)	1	

Table 4: Valid Fits for Average Sojourn Time ($M/M/2$ Queue, with $\rho = 1$)

ARIMA(0, 1, q) FITTED MODEL	TIME INTERVAL		ARIMA(p, 1, 0) FITTED MODEL	TIME INTERVAL	
	$\Delta_t = 0.5$	$\Delta_t = 1.0$		$\Delta_t = 0.5$	$\Delta_t = 1.0$
ARIMA(0, 1, 0)		24	ARIMA(0, 1, 0)		24
ARIMA(0, 1, 1)	78	63	ARIMA(1, 1, 0)	10	46
ARIMA(0, 1, 2)	9	11	ARIMA(2, 1, 0)	44	25
ARIMA(0, 1, 3)	7	1	ARIMA(3, 1, 0)	29	3
ARIMA(0, 1, 4)	1	1	ARIMA(4, 1, 0)	11	2
ARIMA(0, 1, 5)	3		ARIMA(5, 1, 0)	5	
ARIMA(0, 1, 6)	2		ARIMA(6, 1, 0)	1	

captured the marked curvature in the initial behavior of the original series—see Figure 8.

4 CONCLUSIONS AND RECOMMENDATIONS

In this work, we propose an approach that is valid for meaningfully analyzing the output produced by non-stationary stochastic simulations. Based on what we might call *the classical time series method* for simulation output analysis, the approach can be used to obtain effective meta-models,

namely, for queueing system simulation. A significant experimental evaluation of our approach showed that it performed quite well for two queueing systems under critical traffic conditions.

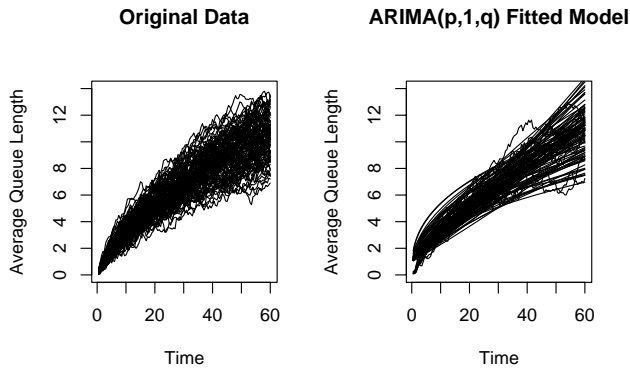


Figure 6: Original and Fitted Series: Average Queue Length ($M/M/2$ Queue, with $\rho = 1$ and $\Delta_t = 0.5$)

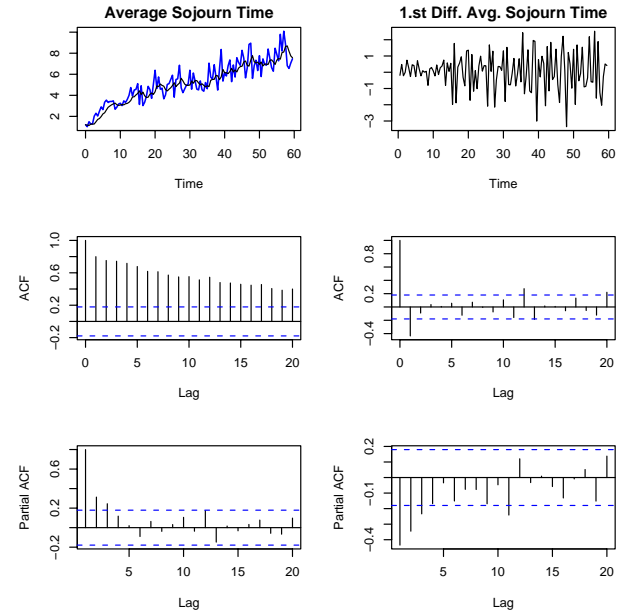


Figure 7: Average Sojourn Time ($M/M/2$ Queue, with $\rho = 1$ and $\Delta_t = 0.5$)

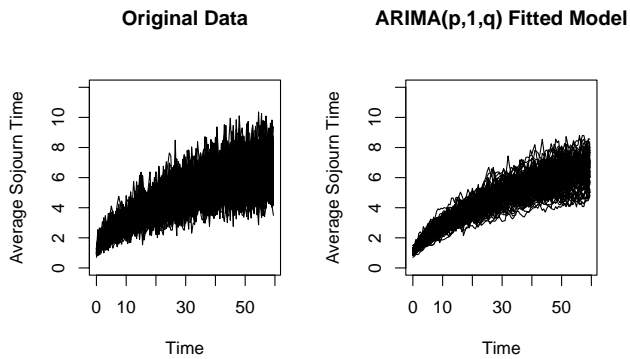


Figure 8: Original and Fitted Series: Average Sojourn Time ($M/M/2$ Queue, with $\rho = 1$ and $\Delta_t = 0.5$)

It is clear that much has to be done to develop and fundament the approach presented here. Also more comprehensive experimental evaluations, new examples of applications, other analytical models relating selected simulation responses with model parameters... However, we feel that this is a very promising area of undoubtedly practical interest, and we intend to continue exploring it.

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