AN AXIOMATIC BASIS FOR GENERAL DISCRETE-EVENT MODELING

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ABSTRACT

The discrete-event technique (DET) is a powerful technique for modeling and simulating dynamic systems. However, with its previous formulations, two problems arise. First, DET models can be difficult to build. DET encourages one to think in terms of the causality relation between events, but provides only indirect means of expressing it. Second, it can be difficult to reason about them, i.e. to prove temporal properties such as safety, not provable by simulation alone. This is because the logic of event occurrences underlying DET is specified only algorithmically, not explicitly. This paper presents DMOD, a new formulation of DET and proposes solutions to the above problems. It also presents an implementation of DMOD models and of the reasoning techniques, using the logic of definite clauses. This logic has high expressive power and simple deductive properties.

1 INTRODUCTION

The discrete-event technique (DET) is a powerful technique for modeling and simulating dynamic systems. Many formulations of it have been proposed, e.g. (Fishman 1973, Zeigler 1984, Evans et al. 1965, Evans 1988, Suri 1987). A number of well known commercial simulation packages e.g. SIMSCRIPT or OPNET are based upon it. DET is based upon the idea that the behavior of a system can be represented by its history, i.e. the sequence of events which occur in it. DET defines a technique for specifying and computing event occurrences.

DET is powerful because it is able to model situations where effects of events depend not just on their past but also on their future. These arise frequently in dynamic systems. For example, in a phone system, an effect of lifting a handset at T is dial tone timing out at $T+3\theta$, provided in between

T and T+30, a digit is not dialed. Such a situation also occurs in, for example, preemptive schedulers.

However, with previous formulations of DET, two problems arise. First, DET models can be difficult to build. This is because DET encourages one to think in terms of the causality relation between events, but allows one to express it only indirectly. Second, it is difficult to reason about DET models. Reasoning is necessary to prove temporal properties, such as safety, which cannot be proved by simulation alone. For example, in the phone system, one may wish to prove that if the time T1 taken by the user to dial a one-digit number is less than the dial tone timeout value T2, connection is assured. Clearly, one cannot simulate for each of the infinite number of pairs <T1,T2>, T1<T2, and check. Instead, one has to analyze the logic of event occurrences. However, this logic is not explicitly specified. Event occurrences are specified only by the simulation procedure, which is algorithmic.

This paper proposes DMOD, a new formulation of DET. It enables the user to directly specify the causality relation between events. Thereby, model building is greatly simplified. DMOD also defines event occurrences in a logical manner, and uses it to build a framework for formulating and proving temporal properties. Although not discussed in this paper, DMOD is powerful enough to model hybrid systems, i.e. those which exhibit both discrete and continuous behavior. An implementation of both DMOD models and the reasoning framework is shown using the logic of definite clauses (Kowalski 1979, Lloyd 1984), the basis of the widely used language Prolog. This logic has high expressive power and simple deductive properties.

Section 1.1 outlines DET and discusses the above problems in some detail. Section 2 presents DMOD. Section 3 discusses an implementation of it using the logic of definite clauses.

Section 4 presents a framework for proving temporal properties, as well as an implementation of it using the above logic.

1.1 Outline of DET

A typical DET model of a system defines:

- A set of time stamped events
- A set of system states
- The relation schedules(S, E, F), meaning that in state S, event E possibly causes event F.
- The relation unschedules(S, E, F), meaning that in state S, event E precludes event F.
- The relation updates(E,S,S1), meaning that event E changes system state S to system state S1.

A history of the system is computed as follows: three data structures, state, clock, event queue are maintained. Where E is the event in queue with the least time stamp, E is removed from queue, and recorded as occurring. clock is set to be the time stamp of E. state is set to be newstate where updates(E, state, newstate). Each event F such that F is in the queue and unschedules(newstate, E, F), is deleted from queue. Each event F such that schedules(newstate, E, F), is inserted into queue. This sequence of steps is repeated to yield a sequence of event occurrences, i.e. history. Computation of history is also called simulation.

For example, suppose we wished to model one aspect of the simple phone system: when a hand set is lifted, the network waits for 30 seconds for a digit to be dialed. If it is not dialed within this time, a time out occurs. Dialing occurs 15 seconds after the hand set is lifted.

We can model events of lifting a handset at T, of dialing at T, and of timing out at T using, respectively, the expressions lhs(T), dial(T), to(T). Now, lhs(T) schedules dial(T+15) and to(T+30). Also, dial(X) unschedules any event of the form to(Y). Let lhs(0) occur. Then, by the above procedure, only dial(15) occurs. However, if lhs(T) were to schedule dial(T+40), and lhs(0) occurs, then both to(30) and dial(40) occur.

It is reasonable to say that schedules/unschedules relations are means to define the causality relation between events. Causality defines a sufficient condition for event occurrence: if E causes F and E occurs, then F

occurs. Thus, "E schedules F but G unschedules F" implicitly means "E causes F provided G does not occur in between."

However, it is difficult to specify causality in this indirect manner. This is because it is difficult to associate a precise meaning with schedules and unschedules. Given that S is the state after E has occurred, schedules(S,E,F) is neither a sufficient nor a necessary condition for occurrence of F. F can be unscheduled. Also, another event in another state can schedule F. Similarly, given that S is the state after E has occurred, unschedules(S,E,F) is neither a sufficient nor a necessary condition for non-occurrence of F. F can be rescheduled. Also, another event in another state can unschedule F.

Furthermore, history is defined only in a procedural manner, not by means of axioms. Thus, it is difficult to show that a property P such as safety, is satisfied by all histories. The traditional approach of starting from axioms defining P and history, and developing a proof using logical principles, cannot be employed.

DMOD proposes solutions to the above problems. For the first problem, DMOD eliminates the scheduling and unscheduling relations in favor of the single causality relation. causes(E,HE,F) means "if HE is the history up to (but not including) E, then E causes F". If E has occurred, then causes(E,HE,F) is a sufficient condition for the occurrence of F.

Situations where effects of events depend on their future can be easily modeled. For example, to model the rule causes(E,HE,F) if G does not occur in between, make E cause an auxiliary checking event check(E,F,TF), where TF is the time stamp of F. This event definitely occurs. When it does, it examines the history up to it to see whether G occurs after E. If so, it causes nothing. Otherwise, it causes F. See Section 3.1 for an example.

For the second problem, DMOD defines history by means of axioms. A history is defined to be a sequence of events satisfying two main conditions, causal soundness and causal completeness. Thus, it becomes possible to understand event occurrences without any reference to event queues. A procedure is also presented for computing histories and, for a wide class of histories, is shown to be equivalent with the axiomatic definition. Event queues are restored in this procedure, but their status as purely efficiency devices is established.

2 DMOD: A NEW FORMULATION OF DET

A DMOD structure is a tuple {Events, TimeS-tamps, time, lt, eq, causes, init_event} where:

- Events is an enumerably infinite set of objects called events.
- TimeStamps is an enumerably infinite set of objects called time stamps.
- time(E,T) is a relation between an event E and a time stamp T. time(E,T) models a function, i.e. is subject to the following existence and uniqueness restriction:

 $\forall E \exists T.time(E,T) \land \forall S.time(E,S) \supset S = T.$

- lt(T1,T2) and eq(T1,T2), T1,T2 time stamps, are relations defining a total ordering between time stamps, i.e. satisfying:
- (1) Exactly one of $\{lt(T1,T2), eq(T1,T2), lt(T2,T1)\}$ holds.
- (2) $lt(T1,T2) \wedge lt(T2,T3) \supset lt(T1,T3)$.
- (3) eq(T1,T1).
- (4) $eq(T1,T2) \supset eq(T2,T1)$.
- (5) $eq(T1,T2) \land eq(T2,T3) \supset eq(T1,T3)$.
- init_event \in Events is called the initial event.
- causes(E, HE, F) is a relation between events E and F, and a finite sequence HE of events in *Events* satisfying:
- (a) $\forall E \forall HE \forall F$, the set $\{F: causes(E, HE, F)\}$ is finite.
- (b) $\forall E \forall HE \forall F$. causes $(E, HE, F) \land time(E, T1) \land time(F, T2) \supset lt(T1, T2) \lor eq(T1, T2)$.

We will use time(E) as an abbreviation for the T such that time(E,T). Where T1,T2 are time stamps, $T1 \le T2$ is an abbreviation for lt(T1,T2) y eq(T1,T2). Similarly for T1 > T2.

Let P be a DMOD structure and S=[E0,E1,...] be a finite, or enumerably infinite sequence of events. Then S is said to be temporally ordered if for each i, $i \ge 0 \supset time(Ei) \le time(Ei+1)$ whenever Ei+1 exists.

We now associate histories with a DMOD structure $P = \{Events, TimeStamps, time, lt, eq, init_event\}$. Let S = [E0, E1, E2,...] a finite or enumerably infinite sequence of events. Then S is

said to be causally-sound, cs(S), if every event in SR has a cause in S, i.e.:

 $\forall j.j > 0 \supset \exists i.i < j \land causes(Ei, [E0,..,Ei-1], Ej).$

Note that the singleton sequence [E0] is trivially causally sound.

Let P be a DMOD structure and S=[E0,E1,E2,...] be a finite or enumerably infinite sequence of events. Then S is said to be causally-complete, cc(S), iff it contains all caused events, i.e.

 $\forall G. \forall i. causes(Ei, [E0,..,Ei-1], G) \supset \exists j.j > 0 \land Ej = G$

Let P be a DMOD structure. A history for P is a finite or infinite sequence H of events such that:

- (a) H begins with init_event
- (b) H is temporally ordered
- (c) No event occurs more than once in H
- (d) H is causally-sound
- (e) H is causally-complete

2.1 A procedure for computing histories

We now present a procedure for computing a subset of histories associated with a DMOD structure $P = \{Events, TimeStamps, time, lt, eq, init_event\}$. Let Seq = [E0, E1,...] be a temporally ordered sequence of events. Then Seq is said to be strictly progressive iff either Seq is finite, or for each time stamp $t \in TimeStamps$ there is an i such that lt(t,time(Ei)). Thus, E0,E1,... is not strictly progressive if time stamps of E0,E1,... are, respectively:

1,2,2,2,2,2,2...

or

 $1, 1+1/2, 1+1/2+1/4, 1+1/2+1/4+1/8, \dots$

where 1,2,+,/ have their usual meanings. In both cases, time stamps converge to 2.

Let S be a set of events. Then $E \in S$ is said to be an *earliest event in S* provided for each event F in S, [E,F] is temporally ordered. Note that if S contains events concurrent with each other there can be more than one earliest event in S. Also, if S is finite, it always contains an earliest event.

Procedure 2.1.1. Let P be a DMOD structure. Record $E\theta = init_event$ as the initial event. Sup-

pose a partial history E0, E1,..., Em, $m \ge 0$, has been computed. We need to compute the next event Em+1. For each i, $0 \le i \le m$, let $Effects_i$ be the set of events F such that:

causes(Ei,[E0,..,Ei-1],F), and F is not already in [E0,E1,..,Em], and [Em,F] is temporally ordered.

Due to the restriction on causes, this set is finite. Let Sm be the union of $Effects_i$, $0 \le i \le m$. Again, this set is finite. If it is empty, halt. Otherwise, it contains an earliest event Em+1. Take this to be the next event. \square

Intuitively, given a partial history H we determine the set Sm of all the events E, not in H, which are caused by an event in H. We pick as Em+1 an earliest event in Sm. Note that Sm can contain more than one earliest event so the procedure is non-deterministic. A different history would be computed for each choice of Em+1.

Sm represents the event queue of the DET procedure prevailing after Em has been computed. In our case, it is reconstructed in its entirety after every event. Thus, considerable inefficiency can result. To alleviate it, we should construct Sm+1 incrementally from Sm. This is done by deleting Em+1 from Sm, and inserting into it all events F such that causes(Em+1,[E0,...,Em],F), F is not in [E0,...,Em+1], and [Em+1,F] is temporally ordered.

We now prove the correctness of Procedure 2.1.1. The correctness of the more efficient version can be similarly proved.

Theorem 2.1. Soundness and Completeness of Procedure. Let $P = \{events, timestamps, time, lt, eq, causes, init_event\}$ be a DMOD structure. Let $E0=init_event$. A strictly progressive sequence of events [E0,E1,...] is computed by the above procedure if and only if it is a history.

Proof: Simple, but omitted for reasons of space.

3 PROGRAMMING DMOD STRUCTURES

Let P be a logic program. We let |-A| be an abbreviation for P|-A, i.e. that there is a proof of A from P. Let R an n-ary relation symbol. Let DI,...,Dn be subsets of HU(P), the Herbrand Universe of P. This is the set of all non-variable terms formed from the function symbols in P, and can be taken to be the set of objects that "the logic program is talking about". Then R is said to

define the relation $\{\langle t1,...,tn\rangle|t1\in D1,...,tn\in Dn \land |-R(t1,...,tn)\}$ upon the set $D1\ X$.. $X\ Dn$, in the presence of P.

Let P be a logic program and D a subset of HU(P). Then seq(D) denotes the set of all finite sequences formed from members of D.

Let an_event and a_time_stamp be two relation symbols. Let events be the set $\{T|T \in HU(P) \land | -an_event(T)\}$. Let timestamps be the set $\{T|T \in HU(P) \land | -a_time_stamp(T)\}$. Note that these two sets can be empty, if there are no clauses defining an_event or a_time_stamp in P.

In the presence of P, let:

- (a) time define time* upon events X timestamps
- (b) lt define lt* upon timestamps X timestamps
- (c) eq define eq* upon timestamps X timestamps
- (d) causes define causes* upon events X seq(events) X events

Let init_event be a member of events. Then {events, timestamps, time*, lt*, eq*, causes*, init_event} is said to be a structure derived from P. Now, P is said to be a DMOD program if there exists a DMOD structure S derived from P.

3.1 Example: Setting Up A Phone Call

We now model the setting up of a call in a simple phone system. When a caller lifts a handset, a dial tone is initiated. The dial tone times out if no number is dialed within a fixed duration. If a number is dialed within this duration, the appropriate phone rings.

We let a time stamp be the term θ or s(X), X a time stamp. Each time stamp denotes a natural number. We use 0,1,2,... as abbreviations for, respectively, 0,s(0),s(s(0)),... The definition of a_time_stamp is:

 $a_time_stamp(X)$ if $natural_number(X)$.

 $natural_number(0)$. $natural_number(s(X))$ if $natural_number(X)$.

Definitions of lt and eq are as follows:

lt(0,s(X)).lt(s(X),s(Y)) if lt(X,Y).

eq(X,X).

The first rule states that θ is less than every

term of the form s(X). The second states that s(X) is less than s(Y) if lt(X,Y). The last defines eq to be syntactic equality. (Note that eq could be defined to hold among non syntactically equal terms, e.g. 2 and l+1).

Addition of natural numbers is defined as follows:

```
plus(0,X,X).

plus(s(X),Y,s(Z)) if plus(X,Y,Z).
```

Where N is a natural number, T a time stamp, and Caller, Called arbitrary terms, an event is of one of the following forms, with meanings given in curly braces:

```
start(0) {The initial event with time stamp 0}

lhs(Caller, Called, T) {Caller lifts handset to call Called at T}

dtto(Caller, T) {Deadline for Caller to dial expires at T}

dials(Caller, Called, T) {Caller dials (single digit) number of Called at T}

rings(Caller, Called, T) {Called gets a ring from Caller at T}
```

The definition of an_event is:

```
an_event(start(0)).

an_event(lhs(Caller,Called,T)) if

a_time_stamp(T).

an_event(dtto(Caller,T)) if

a_time_stamp(T).

an_event(dials(Caller,Called,T)) if

a_time_stamp(T).

an_event(rings(Caller,Called,T)) if

a_time_stamp(T).
```

The time stamp of an event f(t1,...,tn,t) is t. To define time, for each n-ary symbol in $\{lhs, dtto, dials, rings, start\}$ write the definite clause:

```
time(f(T1,..,Tn,T),T).
```

The definition of *causes* is given by the following rules, with informal meanings given in curly braces:

{C1. The initial event causes user(1) to lift his hand set to contact emergency at 100.}

```
causes(E,HE,F) if

E=start(0),

F=lhs(user(1),emergency,100).
```

{C2. When Caller lifts hand set to contact Called, he dials him after delay 4.}

```
causes(E,HE,F) if

E=lhs(Caller,Called,T),

F=dials(Caller,Called,FT),

plus(T,4,FT).
```

{C3. When Caller lifts hand set to contact someone at T, check after timeout delay 3 whether dial tone times out.}

```
causes(E,HE,F) if

E=lhs(Caller,Called,T),

F=check(E,dtto(Caller,FT),FT),

plus(T,3,FT).
```

{C4. Checking whether dial tone times out at T causes dial tone to time out at T provided, in the history since the hand set was lifted, there is no event of Caller dialing.}

```
causes(E,HE,F) if

E=check(G,F,T),

F=dtto(Caller,T),

G=lhs(Caller,Called,PT),

HE=\_*[G]*HG,

absent(dials(Caller),HG).
```

{C5. When Caller dials Called at T, Called hears a ring after a connection delay 5, provided dial tone has not already timed out at Caller.}

```
causes(E,HE,F) if

E=dials(Caller,Called,T),

F=rings(Caller,Called,FT),

plus(T,5,FT),

absent(dtto(Caller),HE).
```

Let f be a function symbol such that for some terms t1,...,tn, f(t1,...,tn) is an event. Then, where H is a sequence of events, absent(f(t1,...,tk),H), $k \le n$ holds iff there is no event of the form f(t1,...,tk,Xk+1,...,Xn) in H. absent is definable using a logic program.

Theorem 3.1.1. *P* is a DMOD program.

Proof. We have to show that the structure derived from P {events, timestamps, time*, lt*, eq*, causes*, start(0)} is a DMOD structure.

The sets *timestamps* and *events* are enumerable as HU(P) is enumerable. As a relation R^* in the given structure is defined by the relation symbol R in P, to prove a proposition Q involving $R^*(t1,..,tn)$, prove Q with $R^*(t1,..,tn)$ replaced by |-R(t1,..,tn)|. For example, to show that:

 $\forall E \forall HE. \{F | causes*(E, HE, F)\}$ is finite

show:

 $\forall E \forall HE. \{F|P|\text{-causes}(E,HE,F)\}\ is\ finite$

The latter can be shown by a case analysis on the form of E. For example, let E be an event lhs(C,N,T). Then, causes(E,HE,F) succeeds once and only once using Rule C2, as plus always succeeds. Similarly for other forms. Similarly, for other propositions. **QED**.

3.2 Computing history for the phone system

We now apply Procedure 2.1.1 to the above DMOD structure. The initial event $E\theta = start(\theta)$. By (Rule) C1:

 $S0 = \{lhs(user(1), emergency, 100)\}, so$ E1 = lhs(user(1), emergency, 100)

By E1,C2 and E1,C3:

 $S1 = \{check(lhs(user(1), 100), dtto(user(1), 103)), dials(user(1), emergency, 104)\}, so$ E2 = check(lhs(user(1), 100), dtto(user(1), 103)).

By E1,C2 and E2,C4:

 $S2=\{dtto(user(1),103), dials(user(1),emergency,104)\},$ so E3=dtto(user(1),103).

By *E1*, *C2*:

 $S3 = \{dials(user(1), emergency, 104)\}, so$ E4 = dials(user(1), emergency, 104).

Note that E4 does not cause an event of ringing at emergency as the occurrence of E3 falsifies the last condition in Rule C5. Thus the history is [E0,E1,E2,E3,E4]. It is easily verified that this is the only history.

4 REASONING ABOUT DMOD STRUCTURES

We now present a framework for expressing and proving properties about DMOD structures. A natural class of such properties is about their histories. Let P be a DMOD structure. Let history(X) be true whenever X is a history for P. Let $X = [E0, E1, \ldots]$ Let prop be a condition upon, possibly infinite, sequences of events. Typically, one proves that prop holds for all histories, i.e.:

$$\forall X.history(X) \supset prop(X).$$
 (A)

A proposition of the form (A) is said to be a liveness property iff prop is of the form:

 $\exists k.cond([E0,..,Ek]).$

where *cond* is a condition upon *finite* sequences of events. Thus, a liveness property states that in every history, there exists some event *Ek* after which *cond* is satisfied.

A proposition of the form (A) is said to be a safety property iff prop is of the form:

 $\neg \exists k.cond([E0,..,Ek]).$

where *cond* is a condition upon finite sequences of events. Thus, a safety property states that in every history, there is never any event *Ek* after which *cond* is satisfied.

We now show how safety properties can be expressed in terms of those involving only finite structures. Thereby, one can contemplate programming any proof procedures one may develop.

Let $P = \{events, timestamps, time, lt, eq, causes, init_event\}$ be a DMOD structure. Let S = [E0, E1, ..., Ek] be a finite sequence of events. Then S is said to be internally causally incomplete, ici(S) iff there exist i, G such that causes(Ei, [E0, ..., Ei-1], G), but G does not occur in S and lt(time(G), time(Ek)).

It is obvious that if S is a finite, initial segment of a history H, then it is *not* internally causally incomplete. If it is, then as H is temporally ordered, G cannot appear after Ek in H. Thus, H is not causally complete.

Let fto(S) be true whenever S=[E0,E1,...,Ek], $E0=init_event$, is a finite, temporally ordered sequence of events in which no event occurs more than once. Suppose we wish to prove a safety property, i.e. that some condition cond does not

hold for any finite initial segment of any history. Then it is sufficient to show:

```
\forall S.fto(S) \land cs(S) \land cond(S) \supset ici(S) (B)
```

Now, let Q be a finite initial segment of a history such that cond(Q). Then, $fto(Q) \wedge cs(Q)$. Hence, by (B), ici(Q). Contradiction.

A brute-force approach for proving B is generating each sequence of events satisfying the left hand side of B, (lhs(B)) and showing that it also satisfies its right hand side. However, except for the most trivial DMOD programs, the set of all sequences satisfying lhs(B) will be infinite. Thus, we cannot hope to explicitly generate each such sequence. If B were true, our approach would not terminate. We can, however, hope to represent an infinite set of sequences by a finite constraint C, and work directly with it. Then, we could still expect termination in finite time.

Should we not be able to show from C that each member of the set represented by it satisfies ici, we could derive from it a finite set of constraints CI,...,Ck such that the union of the sets represented by these is equal to that represented by C. We could then attempt, recursively, to show that each member of Ci satisfies ici.

It is particularly easy to implement this scheme if each constraint is a set $\{A1,...,Ak\}$, each Ai a condition of the form Ri(t1,...,tm) and Ri a relation defined by a logic program. If A1,...,Ak is treated as a query, and if it is transformed in one SLD-step into the queries Q1,...,Qm, then the set of objects represented by $\{A1,...,Ak\}$ is the union of the sets represented by $\{A1,...,Am\}$ is the union of the sets represented by $\{A1,...,Am\}$ satisfies some property, we can construct an SLD-search tree rooted at $\{A1,...,Am\}$. At each node in the tree, a constraint of this form would appear. The deeper the node is, the more "information" it would contain about the objects in $\{A1,...,Am\}$.

It now remains to show that cs, ici, cond and fto are definable using logic programs. For cs we have:

```
cs(Hist) if cs_1(Hist,[]).

cs_1(Hist,Done) if same_events(Hist,Done).
cs_1(Hist,Done) if

Hist=HE*[E]*H,

absent(E,Done),

HE=HF*[F]*HFE,
```

```
causes(F,HF,E), cs_1(Hist, [E|Done]).
```

In $cs_1(Hist, Done)$, Done is a subset of Hist. It is true if all events in Done have a cause in Hist and all remaining events, except the first one in Hist also have a cause in Hist. The second rule states that $cs_1(Hist, Done)$ is true if Hist and Done have the same events. Thes third states that $cs_1(Hist, Done)$ is true if there is an event E in Hist absent in Done which possesses a cause in Hist and $cs_1(Hist, [E|Done])$ is true. Now, Hist is causally sound if $cs_1(Hist, [I])$ is true.

For ici we have:

```
ici(S) if S=HE*[E]*H*[F], causes(E,HE,G), absent(G,S), time(G,TG), time(F,TF), lt(TG,TF).
```

Similarly, fto can easily be defined using logic programs. It only remains to choose cond in such a way that it is definable using logic programs. But a quite wide range of conditions can be defined in this way.

Let P be a DMOD program extended by definitions of cs, ici, fto and cond. Then the proposition:

```
\forall S. fto(S) \land cs(S) \land cond(S) \supset ici(S) reduces to:
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 $\forall S.P|$ -[fto(S) \land cs(S) \land cond(S)] \supset P|-ici(S)

Propositions of this form also arise in questions of logic program equivalence. Hence proof techniques e.g. of (Clark & Tarnlund 1977, Kanamori & Seki 1986, Baudinet 1988) can be utilized.

4.1 Proving properties about the phone system

We now show how our above scheme can be utilized for proving temporal properties about the phone system of Section 3.1. It is easily proved by simulation that the event rings(user(1), emergency, 109) does not occur. However, suppose, that there is a nuisance user(2) who only keeps plugging and unplugging his phone into an outlet at regular time intervals.

His behavior can be expressed using the rules:

```
causes(E,HE,F) \ if \\ E=start(0), \\ F=plugs(user(2),0).
causes(E,HE,F) \ if \\ E=plugs(User,T), \\ F=unplugs(User,T+1).
causes(E,HE,F) \ if \\ E=unplugs(User,T), \\ F=plugs(User,T+1).
```

The first rule initiates the infinite loop, whereas the second and third rules sustain it.

Now, the actions of user(2) have nothing to do with the non occurrence of rings(user(1),emergency,109). Still, to prove by simulation that this event does not occur we would still generate about 100 events for user(2). It is desirable to avoid such inefficiency. Furthermore, suppose that we wanted to prove that no event of the form rings(user(1),emergency,X) ever occurs. This proposition cannot be proved by simulation, as the history is infinite. We could continue forever to generate plugging and unplugging events without realizing that the ringing event cannot occur.

We now show how our proof technique can be used to avoid both the inefficiency and insufficiency of the proof-by-simulation approach. The structure of the proof is as follows: we first prove that if an event dials(user(1), Place, T) occurs then T=104. We do this by assuming that dials(user(1), Place, T) occurs with $T\neq 104$. It must possess a cause. Its only cause is obtained from C2, and is lhs(user(1), Place, T-4). Its only cause is obtained from C1, and is start(0), so T-4=100. Thus, T=104. This contradicts $T\neq 104$.

Now, to prove that rings(user(1),emergency,109) does not occur, we assume it does. Then, by C5, so must its cause dials(user(1),emergency,104), subject to the constraint that no time out event occurs before it. However, by C4 we have a contradiction, since by it a time out event does occur at 103. This is because, by C2, the cause of the dialing event at 104 is one of lifting the hand set at 100. In turn, by C3, this causes an event of checking whether time out occurs at 103. By C4, this causes time out at 103, provided between 100 and 103, no dialing event has occurred. We already established that the only dialing event oc-

curs at 104. We now carry out this proof in detail.

Lemma 4.1.1. Let P be the DMOD structure modeling the phone system, augmented by the three rules for user(2). Let S a finite initial segment of a history. Then, there is no event dials(user(1), Place, T) in S such that $T \neq 104$.

Proof. We have to show:

```
fto(S) \land cs\_1(S,[]) \land S=HE*[E]*H \land E=dials(user(1),Place,T) \land T\neq 104 \supset ici(S).
```

Consider the query:

```
fto(S),

cs\_1(S,[]),

S=HE*[E]*H,

E=dials(user(1),Place,T),

T\neq 104.
```

Replacing $cs_1(S, f)$ for E, we obtain:

```
fto(S),

cs\_1(S, [E]),

S=HF*[F]*HFE*[E]*H,

causes(F,HF,E),

E=dials(user(1),Place,T),

T\neq 104.
```

causes(F,HF,E) can only be expanded, without immediate failure, using Rule C2, to yield:

```
fto(S),

cs\_1(S, [E]),

S=HF*[F]*HFE*[E]*H,

F=lhs(user(1), Place, PT),

plus(PT, 4, T),

E=dials(user(1), Place, T),

T \neq 104,
```

Expanding $cs_1(S, \{E\})$ for F we obtain:

```
fto(S),

cs_{-}1(S, [F, E]),

S=HG*[G]*HGF*[F]*HFE*[E]*H,

causes(G, HG, F),

F=lhs(user(1), Place, PT),

plus(PT, 4, T),

E=dials(user(1), Place, T),
```

T≠104.

causes(G,HG,F) can only be expanded, without immediate failure, using Rule C1 to yield:

```
fto(S),

cs\_I(S, [F, E]),

S=HG*[G]*HGF*[F]*HFE*[E]*H,

G=start(0),

F=lhs(user(1), emergency, 100),

plus(100, 4, T),

E=dials(user(1), emergency, T),

T \neq 104,
```

Expanding plus(100,4,T) to completion, we obtain:

```
fto(S),

cs\_1(S, [F, E]),

S=HG*[G]*HGF*[F]*HFE*[E]*H,

G=start(0),

F=lhs(user(1), emergency, 100),

E=dials(user(1), emergency, 104),

104 \neq 104,
```

But due to the last condition, this query cannot succeed, i.e. it is impossible for S to satisfy the left hand side of the implication at the beginning of the proof. **QED.**

Theorem 4.1.1. Let P be the DMOD structure modeling the phone system, augmented by the three rules for user(2). Let S be a finite initial segment of a history. Then, there is no event rings(user(1), emergency, 109) in S.

Proof. We have to show:

```
fto(S) \land cs_1(S,[]) \land S=HE^*[E]^*H \land E=rings(user(1),emergency,109) \land \supset ici(S).
```

Consider the query:

```
fto(S),

cs_1(S,[]),

S=HE*[E]*H,

E=rings(user(1),emergency,109).
```

Expanding $cs_1(S, f)$ repeatedly, starting at E we obtain:

```
fto(S), cs_1(S, [B, C, D, E]), B=start(0), C=lhs(user(1), emergency, 100), D=dials(user(1), emergency, 104), E=rings(user(1), emergency, 109), S=HB*[B]*HBC*[C]*HCD*[D]*HDE*[E]*H, absent(dtto(user(1)), HB*[B]*HBC*[C]*HCD).
```

Let N=check(C,dtto(user(1),103),103).

Case 1. N is not in S, i.e.:

```
fto(S),
cs\_I(S,[B,C,D,E]),
B=start(0),
C=lhs(user(1),emergency,100),
N=check(C,dtto(user(1),103),103),
D=dials(user(1),emergency,104),
E=rings(user(1),emergency,109),
S=HB*[B]*HBC*[C]*HCD*[D]*HDE*[E]*H,
absent(dtto(user(1)),HB*[B]*HBC*[C]*HCD),
absent(N,S).
```

By Rule C3, $causes(C, HB^*[B]^*HBC, N)$, so due to the last condition, ici(S).

Case 2. N is in S, i.e.:

```
fto(S), cs_{-}I(S,[B,C,D,E]), B=start(0), C=lhs(user(1),emergency,100), N=check(C,dtto(user(1),103),103), D=dials(user(1),emergency,104), E=rings(user(1),emergency,109), S=HB^*[B]^*HBC^*[C]^*HCN^* [N]^*HND^*[D]^*HDE^*[E]^*H, absent(dtto(user(1)),HB^*[B]^*HBC^*[C]^* HCN^*[N]^*HND),
```

Case 2.1. There is no event of the form dials(user(1), Place, T) in HCN, i.e.:

```
fto(S),

cs\_1(S,[B,C,D,E]),

B=start(0),

C=lhs(user(1),emergency,100),

N=check(C,dtto(user(1),103),103),

D=dials(user(1),emergency,104),

E=rings(user(1),emergency,109),

S=HB*[B]*HBC*[C]*HCN*
```

[N]*HND*[D]*HDE*[E]*H, absent(dtto(user(1)), HB*[B]*HBC*[C]*HCN*[N]*HND) absent(dials(user(1)),HCN).

Let HN=HB*[B]*HBC*[C]*HCN. By Rule C4 causes (N,HN,dtto(user(1),103)). Due to the second last condition, ici(S).

Case 2.2. There is an event of the form dials(user(1), Place, T) in HCN. Then $T \le 103$. By Lemma 1, S is not causally sound. **QED**.

Finally, to prove that no event of the form rings(user(1), emergency, X) occurs, we show that if such an event occurs, X=109. The proof is analogous to that of Lemma 1. Now, use Theorem 1.

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